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## APPLICANTS

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## \*\* CONTINUING DATA \*\*\*\*\*

This application is a 371 of PCT/JP04/14626 10/05/2004

## \*\* FOREIGN APPLICATIONS \*\*\*\*\*

JAPAN 2003-349296 10/08/2003  
 JAPAN 2004-259181 09/07/2004  
 JAPAN 2004-259346 09/07/2004

## \*\* IF REQUIRED, FOREIGN FILING LICENSE GRANTED \*\*\* SMALL ENTITY \*\*

10/27/2006

Foreign Priority claimed	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No	<input type="checkbox"/> Met after Allowance	STATE OR COUNTRY	SHEETS DRAWINGS	TOTAL CLAIMS	INDEPENDENT CLAIMS
35 USC 119(a-d) conditions met	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No	Initials	JAPAN	24	4+ 3 s.k.	1

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## TITLE

Self-propelled Working Robot Having Horizontally Movable Work Assembly Retracting in Different Speed  
 Based on Contact Sensor Input on the Assembly

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